Institute for Technology and Management in Construction
Technology and Management for the Decommissioning of Nuclear Facilities
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Autonomous Manipulator for Decontamination Assignments - AMANDA I



Autonomously Climbing Manipulator

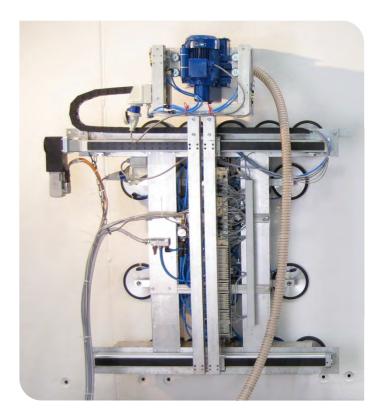
- The autonomously climbing manipulator AMANDA I is a machine for decontamination assignments on wall and ceiling surfaces.
- Modern vacuum technology provides the connection between the manipulator and the object to be treated.
- Primary use of AMANDA I is the decommissioning of nuclear facilities.

Manipulator Processing Head

In order to be able to process the surface according to the requirements, AMANDA is equipped with a milling attachment.

Advantages of the Manipulator

- applicable with high flexibility
- compact design and on demand accuracy
- attachment selectable (e.g. milling attachment, core drilling machine, etc.)
- minimized labor utilization
- remote controlled
- cost efficient (no scaffolding needed)
- especially suited for high an large rooms



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Technical Facts and Figures

Dimensions: 1,30 m x 1,30 m

Weight: 290 kg approx.

Performance: 6m² to 8m², Depending on Motion Pattern

Labor: 1 Operator

Energy Supply: Pressurized Air

Milling Attachment 200m³/h

Ejector Pipe11m³/h

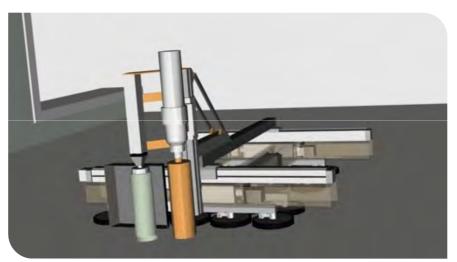
Power Supply 400 V

Wearing Parts: Suction Plates - Robust, Easy to Change

Milling Discs - Minimized Waste

Alternative Attachments

- Core Drilling Machine
- Device for Characterization (Release Measurement)



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